

# NISA - Dymes

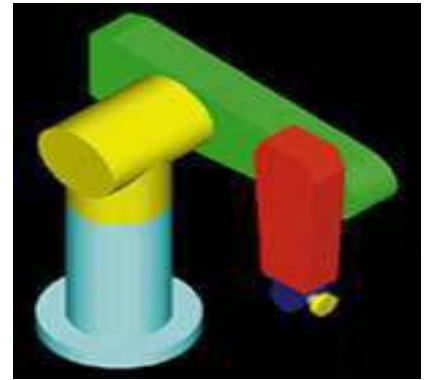
A general purpose program for static, kinematic, and dynamic analyses of constrained multibody mechanical systems undergoing large, nonlinear, three-dimensional displacements. DYMES/Control has been integrated with DYMES for controlled mechanical system simulations.

## HIGHLIGHTS

- Well organized free format input with excellent readability and flexibility for modification
- Integrated with DISPLAY III/IV for model creation and graphical results interpretation
- Enhanced graphics with animation in the post-processor for easy visualization of highly nonlinear motion of complicated mechanisms
- Sophisticated full vehicle or suspension system modeling
- Large library of standard and composite joints for modeling mechanical systems
- Many sophisticated force elements to stimulate cables, springs, dampers, actuators, beams, bushings, etc.
- DYMES/Control for controlled mechanical system simulation



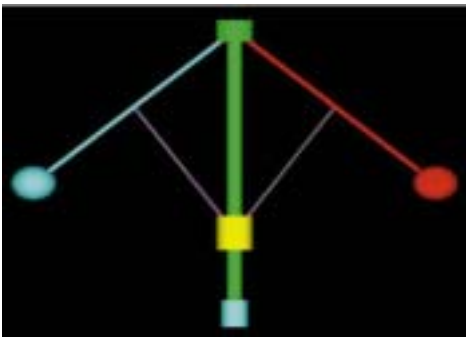
Air Plenum Door Operating Mechanism



Controlled Motion of Puma Robot

## SALIENT FEATURES IN DYMES/Control

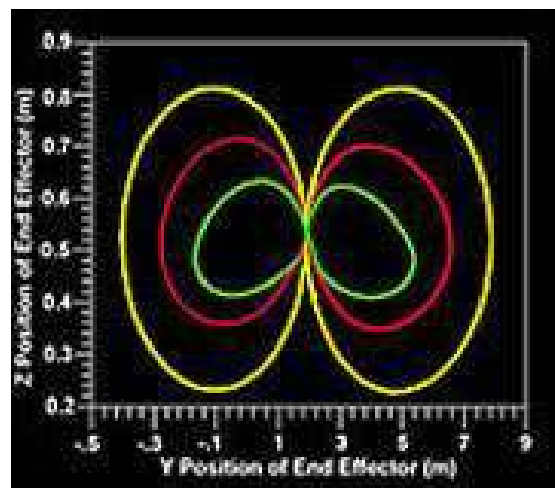
- Single-Input Single-Output (SISO) and Multiple-Input Multiple-Output (MIMO) control system modeling
- Actuation of mechanical system according to controller commands
- Feedback of variables from mechanical system to control system
- Transfer function matrix generation
- Vector import and export of control blocks
- Accessibility of all node and state variables
- Parameter variation study
- Pure control system simulation



Governor Mechanism Motion Analysis

## ANALYSIS CAPABILITIES

- Assembly Analysis
- Redundancy Analysis
- Static Equilibrium Analysis
- Quasi-Static Equilibrium Analysis
- Dynamic Analysis
- Kinematic Analysis
- Inverse Dynamic Analysis



End Effector Trajectories with Different Gain Settings

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### Cranes Software International Limited



**Corporate office**  
4th Floor, Block 1,  
Shankar Naryana Bldg  
#25, MG Road,  
Bangalore - 560 001  
Ph: +91 80 51231275 /6 /7  
Fax: +91 80 51231274

**Bangalore**  
29,7th cross,14th Main,  
Vasanth Nagar,  
Bangalore - 560 052  
India  
Ph: +91 80 22381740 /41  
Fax: +91 80 22268410

**Delhi**  
C -100, Shivalik,  
New Delhi 110 017  
India  
Telefax: +91 11 6674891 /92

**Hyderabad**  
3rd floor, 6-3-346/1, Road.no.1  
Banjara Hills  
Hyderabad 500 034  
Ph: +91 040 55840024 /25 /26  
Telefax: +91 040 5584 0028

**Pune**  
Bldg. B-5, Flat 23, Sr.No.11  
Krishnakeval Township  
Main Kondhwa Road,  
Kondhwa,  
Pune 411 048  
Tel: +91 020 26837074,  
Fax: +91020 26832793

**Trivandrum**  
Megabyte Royal Business Centre,  
Cabin 508, 5th Floor  
Karimpanal Statue Avenue  
GH Road, Statue  
Trivandrum 695 001  
Tel: +91 0471 3094541,  
Fax: +910471 2467855